

SUMMARY

I work full-time as a CV/ML engineer at RoadAR Inc. My main expertise as a CV engineer is object detection and semantic/panoptic segmentation, but I also have experience with key-point detection and StyleGANs. Lately, I have shifted my focus to being an ML engineer to bridge the gap between raw model inference and business objectives.

EDUCATION

INNOPOLIS UNIVERSITY

2016-2020

BACHELOR'S DEGREE IN COMPUTER SCIENCE WITH MAJOR IN DATA SCIENCE

- The first two years covered general CS topics and the following two years covered Data Science subjects.
- Final GPA: 3.36. A full transcription is available [here](#).

EXPERIENCE

ROADLY

July 2020 - Now

COMPUTER VISION/MACHINE LEARNING ENGINEER

The main focus of RoadAR products is the automation of asset inspection using regular smartphone cameras. Projects:

- **Traffic Estimation and Road Accidents** - Data gathering, training object detection model and exporting it for edge devices
- **Road Guide-rails Inspection** - Architecture of model, data gathering, managing data annotation and semantic segmentation model training
- **SLAM Platform** - Container for fast semantic/panoptic/instance segmentation
- **Road Asset Inspection** - 3D mapping of assets, road modeling, BEV camera estimation, inference optimization, Back-end development, and database architecture
- **Traffic Signs Detection** - StyleGAN for generation of underrepresented traffic signs
- **System for Identifying Lost Pets** - Dog face key-point detection

X5 RETAIL GROUP

June 2019 - July 2019

MACHINE LEARNING INTERN

- **Classification and analysis of IT Support work** - Data preprocessing and classification of dialogues using Unsupervised ML

X5 RETAIL GROUP

February 2019 - April 2019

MACHINE LEARNING PROJECT

- **Classification and analysis of the shoppers at the grocery store** - Scraping needed info from cash register logs, preprocessing data, finding text features, and implementing models.

HACKATONS

HAPPYWHALE

March-April 2022

KAGGLE COMPETITION - 18TH PLACE

- **Whale and dolphin re-identification** using their distinct features, such as dorsal fins. Our team managed to get 18th place by training multiple models, combining them with MLP, and using ArcFace as a loss function. Each of the teammates had performed EDA, field exploration, and model training,

ROADHACK

November 2021

CODENROCK HACKATON - 1ST PLACE

- **LIDAR semantic segmentation for road distresses**. Our team had trained segmentation models for cracks and potholes and processed point clouds in under two days delivering the desired results. I was responsible for data gathering, model training, and partially for road model estimation.

SKILLS

PROGRAMMING LANGUAGES	Proficient: Python Familiar: SQL Bash Regexp C++ Haskell Scala Java
SOFTWARE DEVELOPMENT	Docker Git ClearML WandB CVAT Agile
FRAMEWORKS & LIBRARIES	ffmpeg pandas matplotlib fiftyone streamlit FastAPI hydra
DS FRAMEWORKS	Classical CV Pytorch MMCV OpenCV Ffmpeg ONNX OpenVino
LANGUAGES	Native: Russian Fluent: English
HOBBIES	Table Games Smart Homes Self-Hosting